### **MOLECULAR DYNAMICS INVESTIGATION OF FOLDING AND NANOMECHANICAL** CHARACTERIZATION OF AN α-HELICAL PEPTIDE KR1 <u>Aleksandra Wosztyl<sup>1</sup></u>, Krzysztof Kuczera<sup>2,3</sup>, Robert Szoszkiewicz<sup>1</sup> **Faculty of Chemistry** KANSAS University of Warsaw <sup>1</sup>Faculty of Chemistry, Biological and Chemical Research Centre, University of Warsaw, Poland <sup>2</sup>Department of Chemistry, University of Kansas, Lawrence, USA

<sup>3</sup>Department of Molecular Biosciences, University of Kansas, Lawrence, USA Szoszlab a.wosztyl@student.uw.edu.pl 0 1 2 3 4 5 6 7 8 9 1 Fig. 4. RMSD for trajectory starting from extended peptide structure. LYX Fig. 3. GROMACS molecular dynamics simulation workflow with a brief description of the function of each step. with no hydrogen bonds. Partially folded Initial input data: structure in Protein Data Bank (.pdb) file format 0,0 0,1 0,2 0,3 0,4 0,5 0,6 0,7 0,8 RMSD [nm] structure of the peptide, C-terminus amino acid modification Fig. 5. Histogram of RMSD for trajectory Topology file (.top) and GROMACS starting from extended peptide Gly-Asn-Ala-Ala-Gln-Ala-Ala-Ala-Ala-Gln-Ala-Ala-Gly-NH<sub>2</sub> coordinate file (.gro) structure – represents average states Propability population. p [a.u.] CHARMM36-mar2019 force field, TIP3P water model Solvatation of the system See construction of an empty cubic box Fig.5. around the atoms filling the box with solvent. 1st Neutralize the system with ions method at physiological ionic strength 0.007 the conformation of the initial structure from which the simula-0.788adding Na<sup>+</sup> and Cl<sup>-</sup> ions to the syster to obtain physiological ionic strength tion started – in the first case it was an unnaturally 0.205 0 1 2 3 4 5 6 7 8 9 10 0.15 M and an electrically neutral box Time [us] Energy minimization extended structure (see Fig. 1.), and in the sewerage hydrogen Fig. 6. RMSD for trajectory starting 2nd bond population [Steepest Descent algorithm] from  $\alpha$ -helical peptide structure. method cond case, the trajectory was started by an 0.0487 For the lowering the forces acting on atoms relaxing any excessive force introduced The way artificially generated, ideal  $\alpha$ -helix (see in building the system Molecular dynamics with position restraints Fig. 2.). In both trajectories, the time course [Leap-frog algorithm] Other included algorythms was 10µs. The whole process of preparing further relaxation of the system (solvent Berendsen temperature coupling. and ions) wihout destruction of the state Partially folded state Vinitial solute/protein conformation. Propability the system was presented in Fig 3. In the Fig. 2. The KR1 peptide Equilibration of the system p [a.u.] ideal α-helix [Leap-frog algorithm] 0.006 Other included algorythms conformation. relaxation of peptide and buffer structure, the system preparation process was tochastic velocity rescaling 0,0 0,1 0,2 0,3 0,4 0,5 0,6 0,7 0,8 1st 0.889 performing 100 ps MD at constant Parrinello-Rahman pressure coupling, RMSD [nm] method temperature and pressure (NPT MD). 0.105 Fig. 7. Histogram of RMSD for trajectory 10µs trajectory generation starting from  $\alpha$ -helical peptide Average hydrogen [Leap-frog algorithm] 2nd bond population structure – represents average states method Other included algorythms Stochastic velocity rescaling

ABSTRACT The scientific knowledge that mankind has at its disposal enables us to study the interactions that occur in biological molecules in the nanoscale. Nevertheless, what about the entire dynamic process of conformational changes? Is it possible to characterize the short peptide folding process by the fluctuation of nanomechanical parameters? In this work, a short sytnthetic peptide has been used and its folding and unfolding events have been simulated. All this attempt have been made to obtain nanomechanical constants of the peptide in its folded and unfolded confgurations.

**SYSTEM PREPARATION** The simulated KR1 peptide is described by sequence of 13 amino acids and blocking C-terminus amidated group, what can be denoted in three letter symbols: In the project, two simulations of folding trajectory of the  $\alpha$ -helical KR1 peptide were carried out. In both cases simulations were performed in the CHARMM36 force field in an aqueous environment (TIP3P water model) by using GROMACS software. The main difference between the two cases was mize with unnatural stres- case of trajectory starting from the extended performed twice in order to minimize unnatural stresses in the conformation (see Fig. 1.).



Fig. 1. The KR1 peptide extended conformation with the structure minises in the conformation

# SUMMARY

• The two 10 µs peptide folding trajectories were successfully obtained. It is possible to describe the system by the nanomechanical constants – elastic spring constant, mechanical and energy dissipation constant. •The KR1 peptide occurs most of the time in the unfolded state. These conformations constituting a global minimum.

•The constants obtained for the KR1 peptide differ depending on the trajectory. Longer simulations should be performed to obtain better estimates of the constants. •It is necessary to verify the obtained results experimentally.



[1] J. Greenfield. Analysis of the kinetics of folding of proteins and peptides using circular dichroism. Nature protocols, 1(6):2891–2899, 2006. [2] P. Atkins, J. de Paula, and R. Friedman. Quanta, matter, and change: A molecular appraoch tophysical change. W.H. Freeman & Company, 2009. [3] H. C. Berg. Random walks in biology. Princeton University Press, 1st edition edition, 1993.

[4] P. Atkins, J. de Paula, and J. Keeler. Atkins' Physical chemistry. Oxford University Press, 11th edition edition, 2018. [5] Khatri et al., B. S. Entropy and barrier-controlled fluctuations determine conformational viscoelasticity of single biomolecules. Biophysical journal, 92(6):1825-1835, 2007.

[6] H. Dietz et al. Anisotropic deformation response of single protein molecules. Proceedings of the National Academy of Sciences of the United States of America, 103(34):12724–12728, 2006.

[7] N. Kurochkina. Protein Structure and Modeling. Springer Singapore, 2019.



# CHARACTERIZATION



with 5 hydrogen bonds.



d) 6<sup>th</sup> representation of clustering e) 9<sup>th</sup> representation of clustering with 2 hydrogen bonds

| peptide struc  | ture  |   |   |  |  |  |
|--|---|---|---|--|--|--|
|  | Nanomechanical properties   |   |   |  |  |  |
| e diffusion<br>pefficient<br>D [cm <sup>2</sup> /s]<br>[3][7]                          | Mechanical energy dissipation constant<br>ζ [kg/s]<br>[4][5]              |   | Elastic spring constant<br>κ [pN/nm]<br>[5][6]  |  |  |  |
| $= \frac{\delta^2}{2 \times \tau_1}$<br>distancealong<br>helical axis<br>yeen residues | $\zeta = \frac{k_B T}{D}$ $k_B$ -the Boltzmann constan; T – tempe- rtaure | $\begin{split} \zeta &= \frac{k_BT}{(\Delta x_{s_1 \longleftrightarrow s_2})^2} (\frac{1}{k_1} + \frac{1}{k_{-1}}) \\ \Delta \mathbf{x} \text{ - the distance to the transition} \\ \text{state} \end{split}$ | $\kappa = \frac{k_BT}{(\Delta x)^2} \frac{1}{p(1-p)}$<br>$\Delta \mathbf{x}$ - the distance to the transition state | $\kappa = 2 \frac{-k_B T \times ln(\frac{k_{-1}}{k_A})}{(\Delta x_u)^2}$<br>$\Delta x \text{ - the distance to the transition state}$<br>$k_A \text{ - Arrhenius frequency}$<br>factor |  |  |
|  |   | 2.332<br>×10 <sup>-9</sup>  | 5212.15   | 566.27   |  |  |
| 4.65<br>×10 <sup>−8</sup>  | 0.891<br>×10 <sup>-9</sup>  | -   | -   | -  |  |  |
|  |   | 2.809<br>×10 <sup>-9</sup>  | 337.84  | 4523.56  |  |  |
|  |   | 2.357<br>×10 <sup>-9</sup>  | 801.43  | 572.17   |  |  |

| peptide struc  | ture   |                            |  |         |  |  |
|--|--|----------------------------|--|---------|--|--|
|  | Nanomechanical properties                                    |                            |  |         |  |  |
| e diffusion<br>oefficient<br>D [cm <sup>2</sup> /s]<br>[3] | Mechanical energy dissipation constant<br>ζ [kg/s]<br>[4][5] |                            | Elastic spring constant<br>κ [pN/nm]<br>[5][6] |         |  |  |
| 6.66<br>×10 <sup>-8</sup>                                  | 0.622<br>×10 <sup>-9</sup>                                   | 1.747<br>×10 <sup>-9</sup> | 7011.10  | 524.65  |  |  |
|  |  | -                          | -  | -       |  |  |
|  |  | 1.754<br>×10 <sup>-9</sup> | 422.71   | 4661.36 |  |  |
|  |  | 1.649<br>×10 <sup>-9</sup> | 1075.16  | 529.42  |  |  |

### **BIBLIOGRAPHY**